# **TRANSPORTATION LEARNING NETWORK** A partnership with MDT·NDDOT·SDDOT·WYDOT and the Mountain-Plains Consortium Universities

Welcome!



Inferencing Traffic Volume using Data-Driven Machine Learning and Graph Theory

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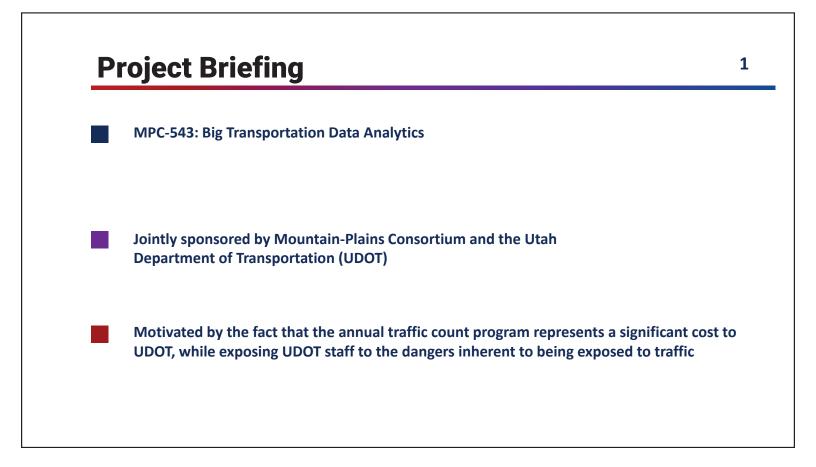
Our partners:

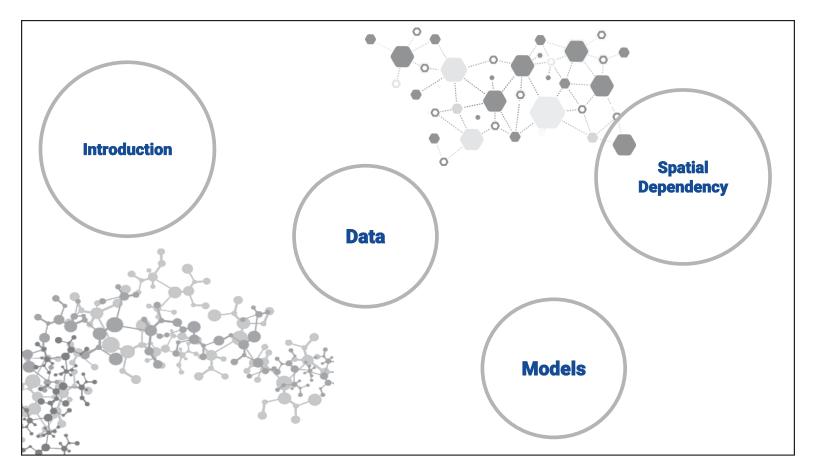


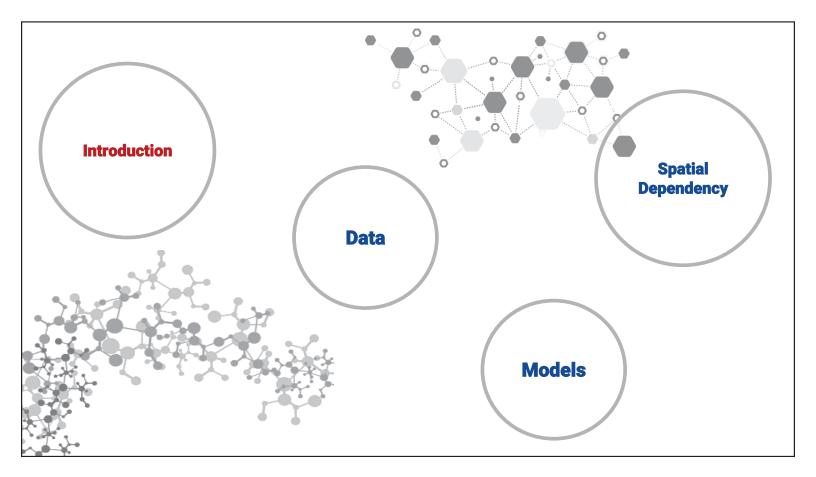


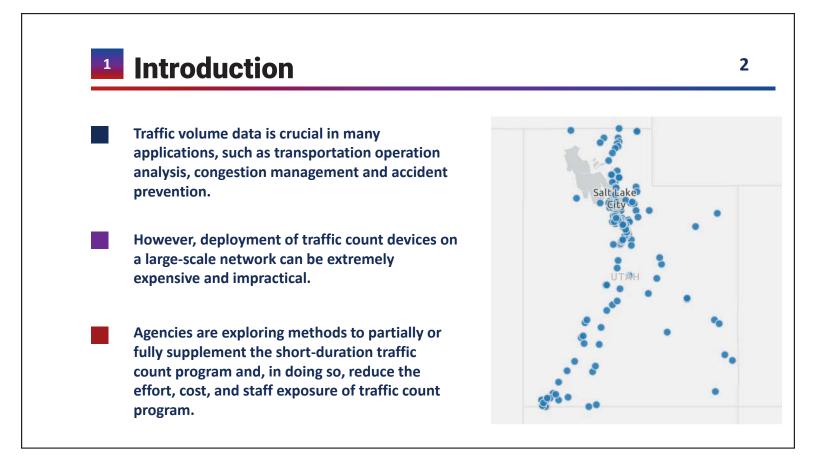
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# Introduction

How to accurately estimate/predict traffic volume without massive sensor deployment?

Two branches of volume estimation problem:

- Future traffic volume prediction at locations equipped with traffic sensors
- Generally involves estimation of immediate future volume at the same locations within a short time period based on historical information.
- Commonly used methods: Auto-regressive integrated moving average (ARIMA) and its variants (e.g. SARIMA)

# 1 Introduction

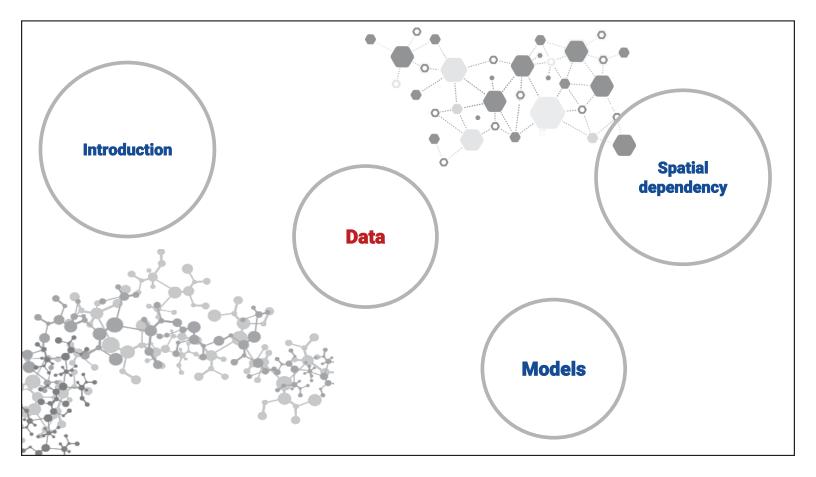
Two branches of volume estimation problem:

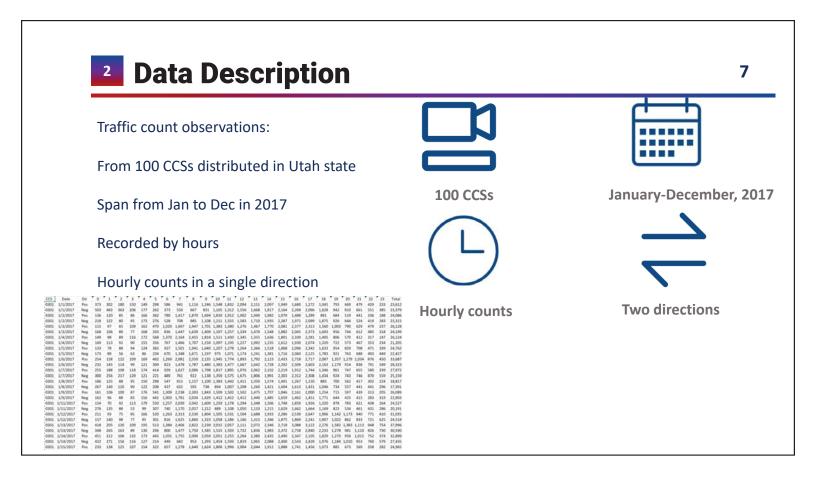
- Traffic volume estimation: spatial traffic volume prediction
- Spatial prediction usually aims at estimating traffic volumes at locations without sensors.
- Commonly used methods: Factoring method Regression model Machine learning model

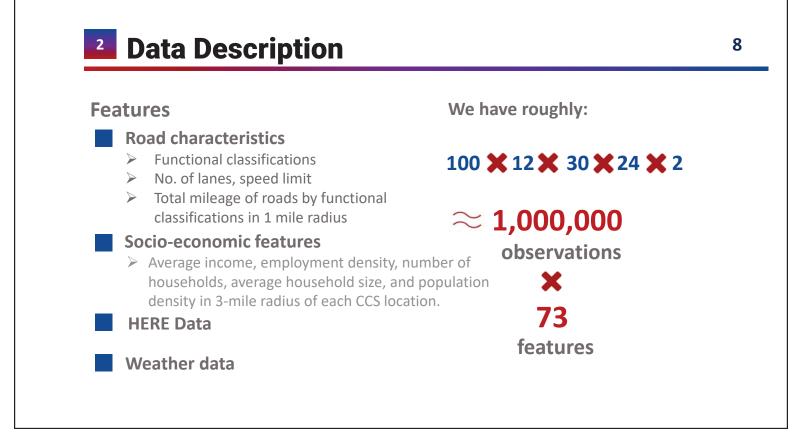
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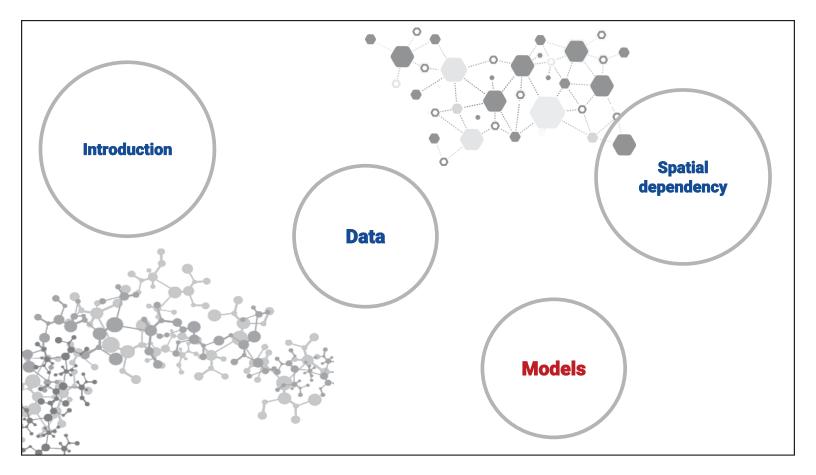
# Objectives

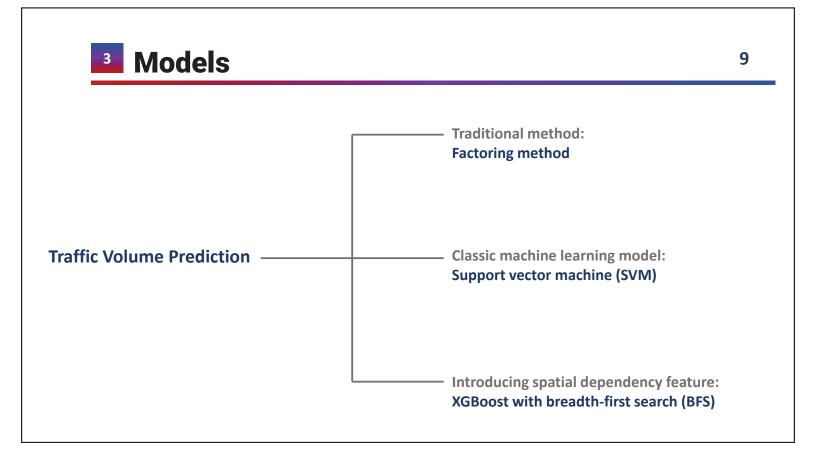
- Explore ML techniques to predict hourly traffic volumes using features that are associated with the variation of traffic volume, and compare against conventional methods
- Enhance the prediction accuracy by exploring methods to quantify the spatial dependency among road segments











# Models - Factoring Method

### • The basic idea:

A year's AADT was estimated from short-term count (48 hours in continuous) using the formula from Traffic Monitoring Guide (FHWA 2001):

$$AADT_{est,i} = \frac{1}{2} \sum_{d=1}^{2} VOL_i * M_i * D_i * G_i$$

*Vol*<sub>*i*</sub>: actual 24-hour vehicle count

 $D_i$ : day of week factor

 $M_i$ : seasonal factor

 $G_i$ : traffic growth factor

# Models - Factoring Method

• The basic idea:

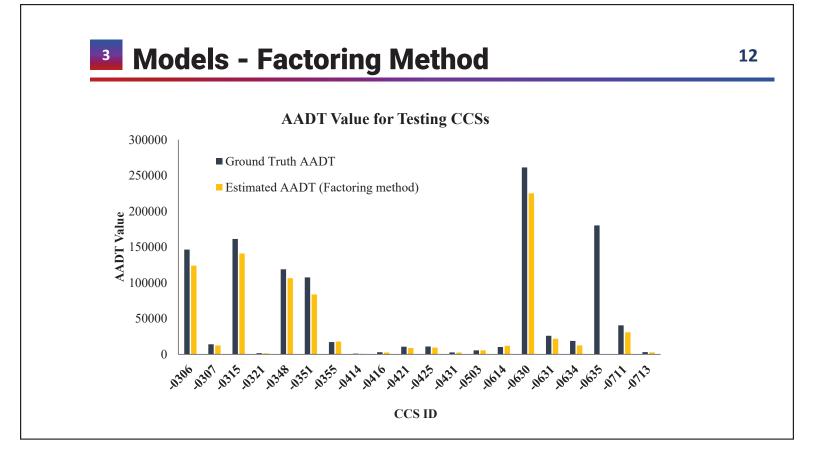
A year's AADT was estimated from short-term count (48 hours in continuous) using the formula from Traffic Monitoring Guide (FHWA 2001)

• Advantages:

Simple and straightforward

• Disadvantages:

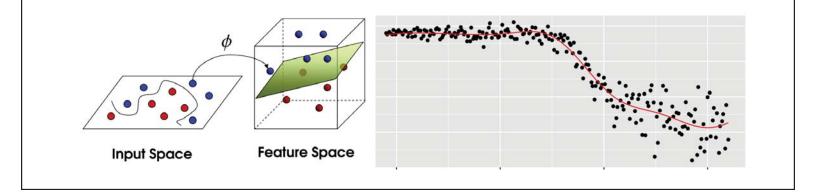
Large random errors

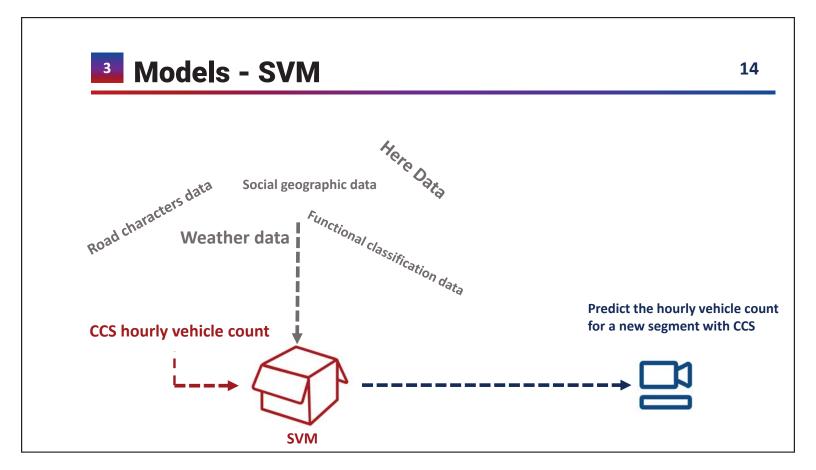


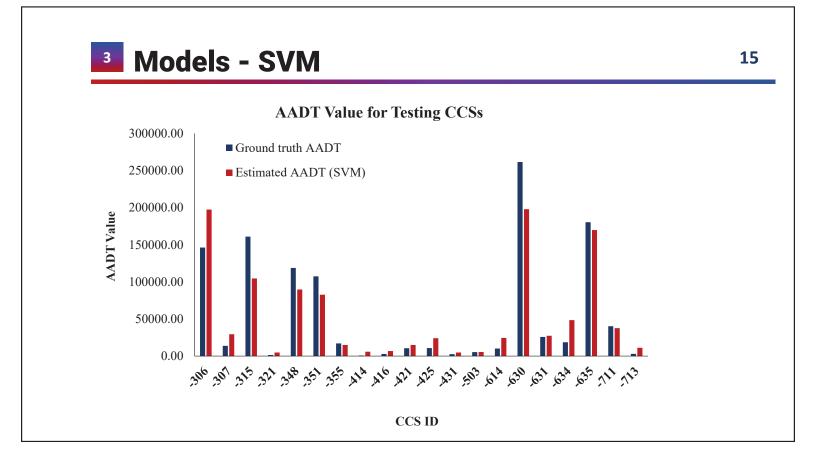
# <sup>3</sup> Models - SVM

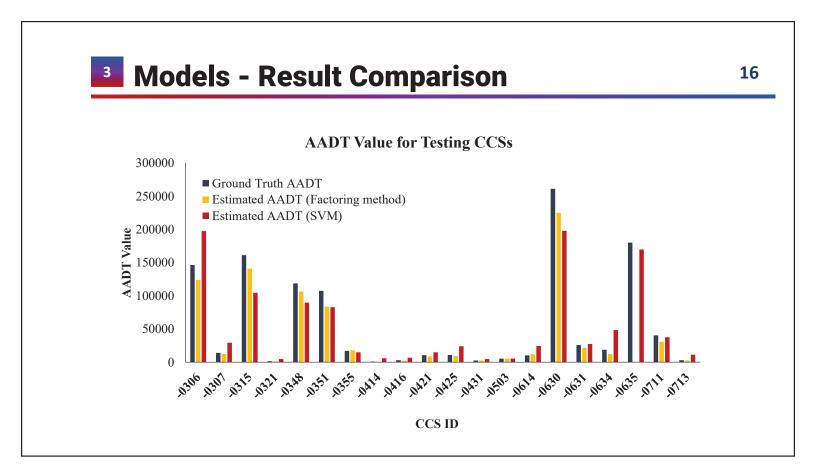
### • The basic idea:

A model that constructs hyperplanes on higher dimensional space to solve classification and regression problems (proposed by Cortes and Vapnik in 1995)









# <sup>3</sup> Models-SVM

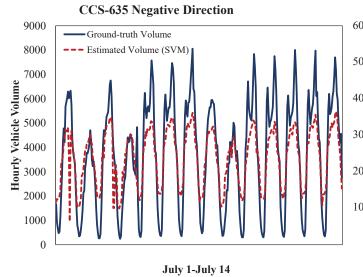
AADT is a traffic volume indicator on a coarse level.

SVM is capable of predicting traffic volume information by hour-a smaller granular level.

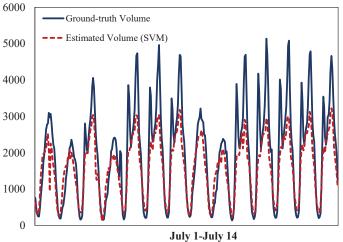
We have the data of **100 CCSs** in total. Among them, **80 CCS** are used to train the model and **20 CCSs** are used to test the effectiveness of the model.

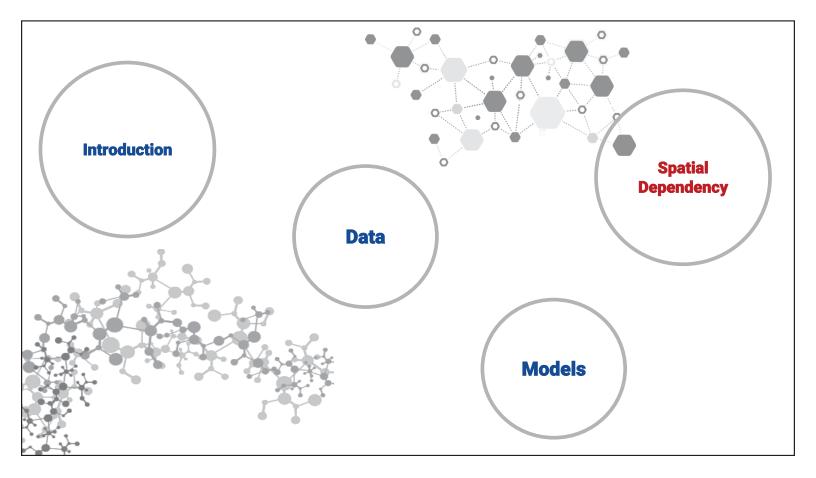
## <sup>3</sup> Models-SVM

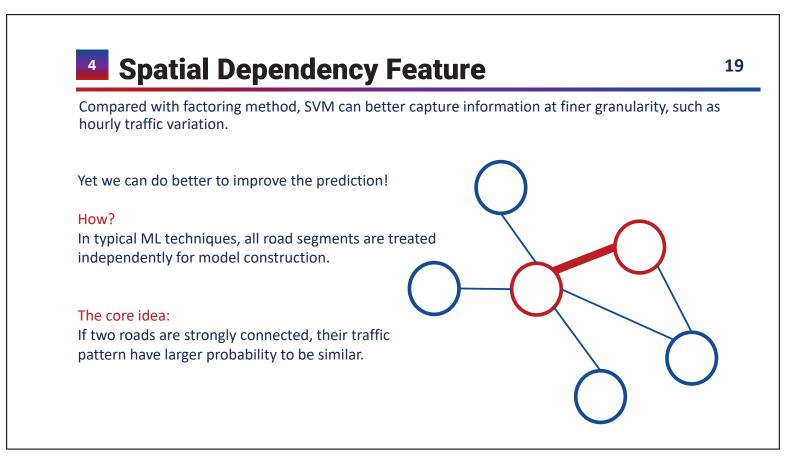
To visualize the results, we use the ground-truth hourly counts and the predicted values from SVM for comparison. Here, we visualize the data from two randomly chosen CCSs in consecutive 14 days (CCS 635 and CCS 351).

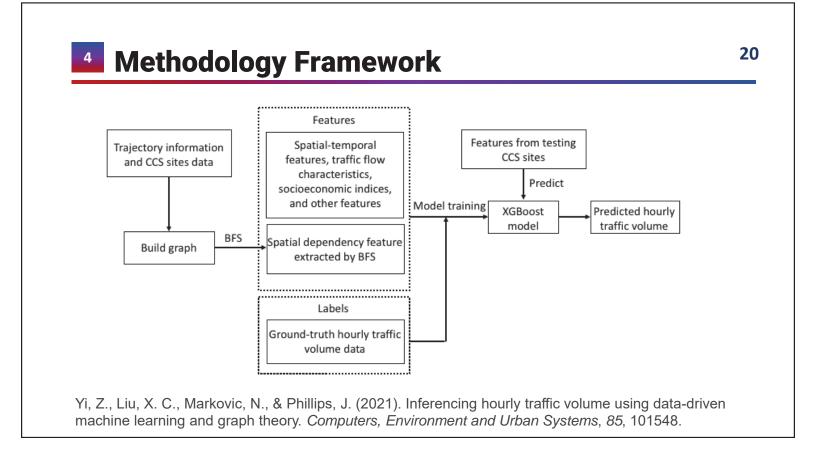


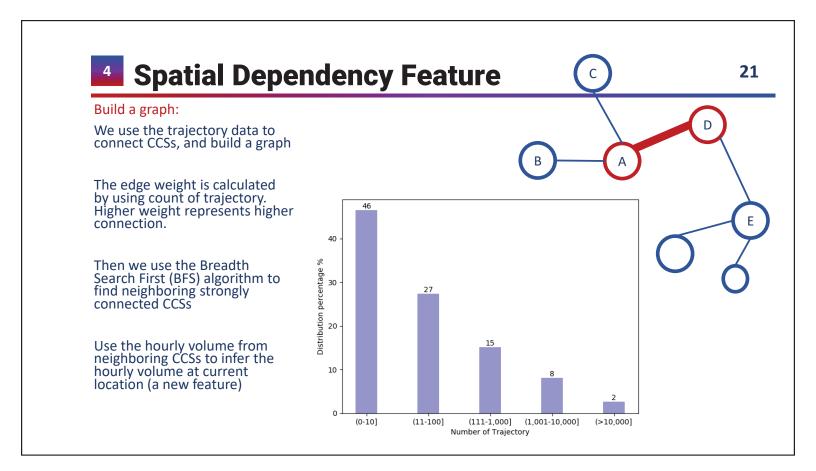
### **CCS-351** Negative Direction

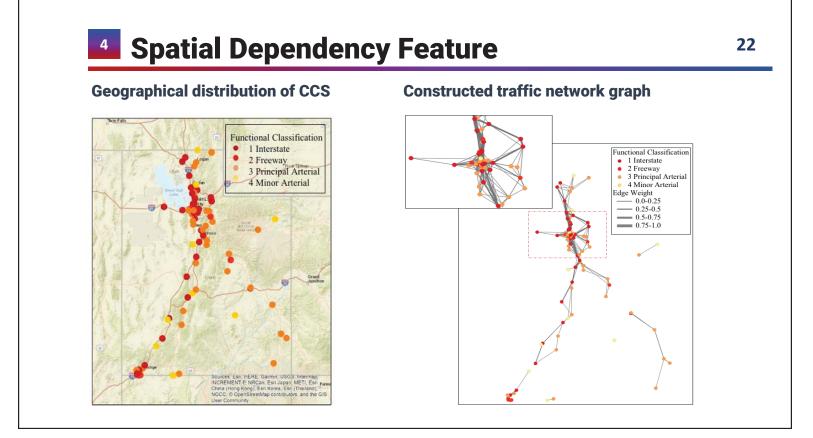


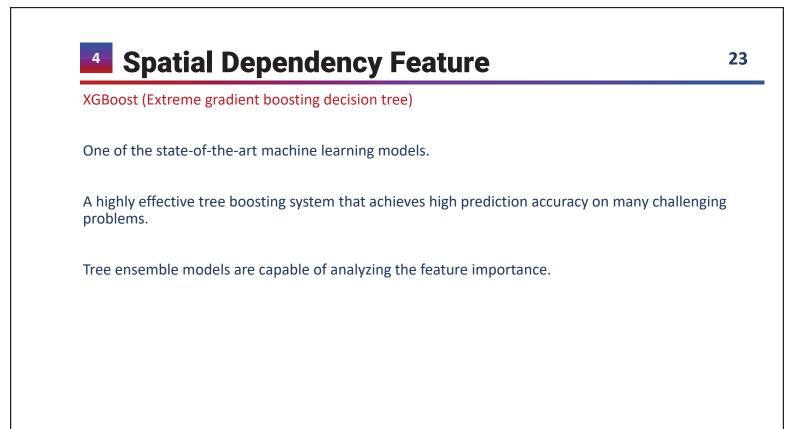












# Spatial Dependency Feature

Performance metrics:	Name of measurement	Mathematical formulation	n Brief description		
R <sup>2</sup> , MAE, MAPE	$R^2$	$R^{2} = 1 - \frac{\sum_{i=1}^{n} (y_{i} - \hat{y}_{i})^{2}}{\sum_{i=1}^{n} (y_{i} - \bar{y})^{2}}$	$R^2$ is the proportion of traffic volume variance that is explained by predicting models, and it provides a measure of how well observed outcomes are replicated by the model.		
Testing process:	MAE	$MAE = \frac{1}{n} \sum_{i=1}^{n}  y_i - \hat{y}_i $	MAE is a measure of difference between actual values and predicted values, which gives a clear interpretation of average magnitude of the errors for predictions.		
replicated 5 times by different random seeds In each seed, 15% CCSs are selected as testing site	MAPE	$MAPE = \frac{1}{n} \sum_{i=1}^{n} \left  \frac{y_i - \hat{y}_i}{y_i} \right $	MAPE is a statistical measure of prediction accuracy, where the prediction error is presented as a percentage. Smaller values indicate better prediction power.		

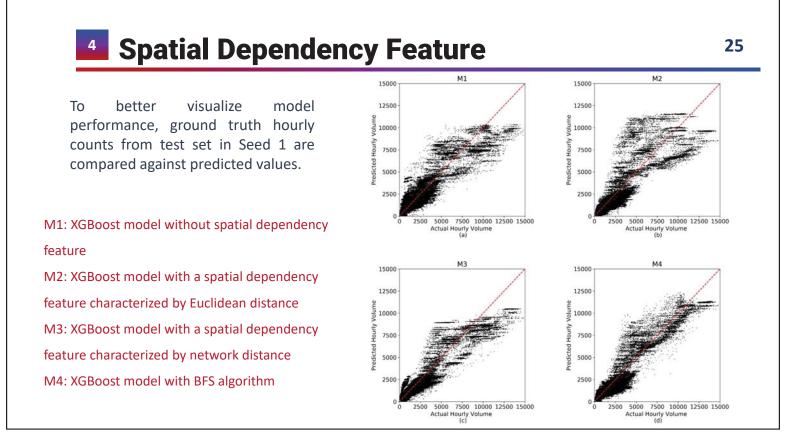
Model comparison:

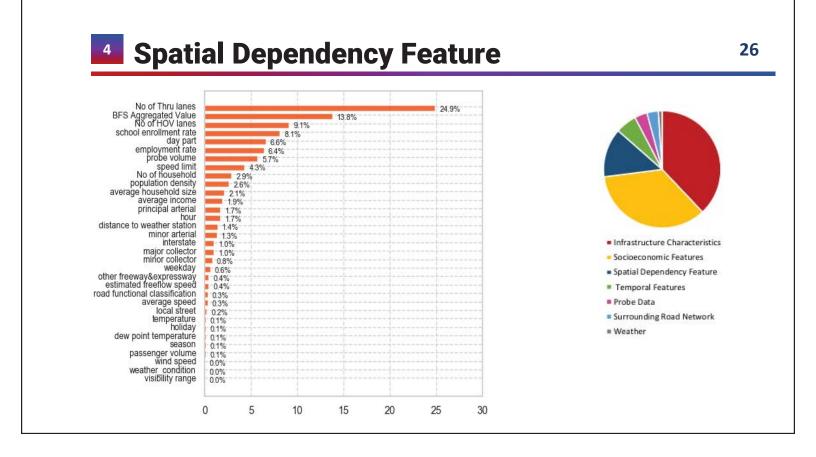
M1: XGBoost model without spatial dependency feature

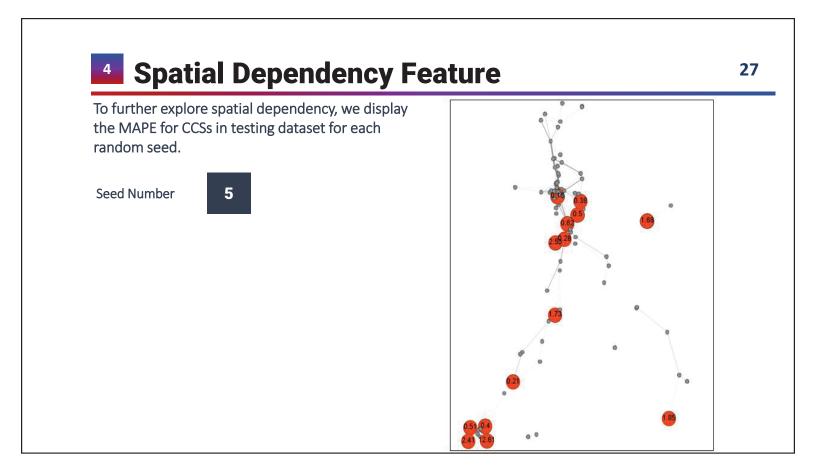
M2: XGBoost model with a spatial dependency feature characterized by Euclidean distance

M3: XGBoost model with a spatial dependency feature characterized by network distance

Seed	$R^2$ on test set			MAE on test set			MAPE on test set					
	M1	M2	M3	M4	M1	M2	M3	M4	M1	M2	M3	M4
1	0.849	0.780	0.860	0.895	643	720	619	548	0.80	0.56	0.65	0.57
2	0.839	0.862	0.811	0.934	645	554	562	404	1.06	0.93	0.51	0.88
3	0.817	0.875	0.879	0.885	887	773	799	733	1.26	0.57	0.68	0.52
4	0.859	0.866	0.847	0.868	631	397	420	522	1.96	1.03	1.58	1.33
5	0.898	0.831	0.936	0.916	347	681	311	308	2.09	1.66	1.07	1.67
Mean	0.852	0.842	0.866	0.900	631	625	542	503	1.43	0.95	0.90	0.79







# **5** Conclusions



Both traditional methods and machine learning models generate satisfactory results for predicting AADT.



Machine learning models (e.g. SVM and XGBoost) are capable of capturing hourly traffic volume.



Incorporating spatial dependency feature can improve the prediction accuracy.



Road characteristics, socioeconomic factors, spatial dependency, and temporal features are the most influential feature categories.

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We appreciate your feedback.

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